



UNDERSTANDING AND INTERPRETING PARTICLE SIZE DISTRIBUTION CALCULATIONS

Performing a particle size analysis is the best way to answer the question: *What size are those particles?* Once the analysis is complete the user has a variety of approaches for reporting the result. Some people prefer a single number answer – what is the average size? More experienced particle scientists cringe when they hear this question, knowing that a single number cannot describe the *distribution* of the sample. A better approach is to report both a central point of the distribution along with one or more values to describe the width of the distribution. Other approaches also exist as described in this document.

Central Values:

Mean, median, mode

For symmetric distributions such as the one shown in Figure 1 all central values are equivalent:

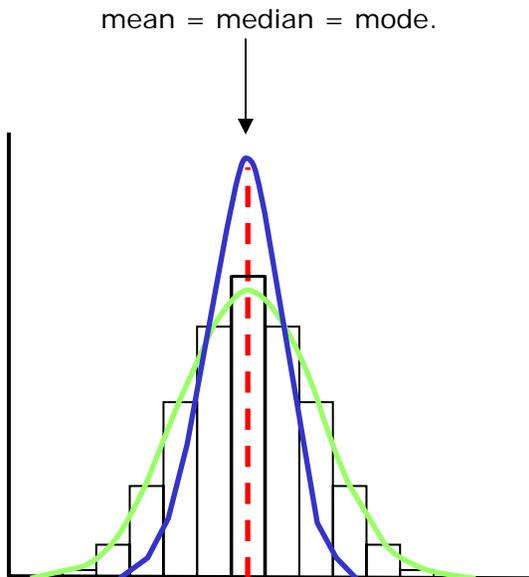


Figure 1: A symmetric distribution

But what do these values represent?

Mean

Mean is a calculated value similar to the concept of average. The various mean calculations are defined in

several standard documents (1,2).

There are multiple definitions for mean because the mean value is associated with the basis of the distribution calculation (number, surface, volume). See (3) for an explanation of number, surface, and volume distributions. Laser diffraction results are reported on a volume basis, so the volume mean can be used to define the central point although the median is more frequently used than the mean for laser diffraction results. The equation for defining the volume mean is shown below. The best way to think about this calculation is to think of a histogram table showing the upper and lower limits of n size channels along with the percent within this channel. The D_i value for each channel is the geometric mean, the square root of upper x lower diameters. For the numerator take the geometric D_i to the fourth power x the percent in that channel, summed over all channels. For the denominator take the geometric D_i to the third power x the percent in that channel, summed over all channels.

$$D[4,3] = \frac{\sum_1^n D_i^4 v_i}{\sum_1^n D_i^3 v_i}$$



The volume mean diameter has several names including D_{4,3}. In all HORIBA diffraction software this is simply called the “mean” whenever the result is displayed as a volume distribution. Conversely, when the result in HORIBA software is converted to a surface area distribution the mean value displayed is the surface mean, or D_{3,2}. The equation for the surface mean is shown below.

$$D[3,2] = \frac{\sum_1^n D_i^3 v_i}{\sum_1^n D_i^2 v_i}$$

The description for this calculation is the same as the D_{4,3} described above, except that the D_i values are raised to the exponent values of 3 and 2 instead of 4 and 3.

The generalized form of the equations seen above for D_{4,3} and D_{3,2} is shown below (following the conventions from ref. 2, ASTM E 799,).

$$\bar{D}_{pq}^{(p-q)} = \frac{\sum D_i^p}{\sum D_i^q}$$

Where:

\bar{D}	= the overbar in D designates an averaging process
$(p-q)p > q$	= the algebraic power of D_{pq}
D_i	= the diameter of the <i>i</i> th particle
Σ	= the summation of D_i^p or D_i^q , representing all particles in the sample

Some of the more common representative diameters are:

\bar{D}_{10}	= arithmetic or number mean
\bar{D}_{32}	= volume/surface mean (also called the Sauter mean)
\bar{D}_{43}	= the mean diameter over volume (also called the DeBroukere mean)

The example results shown in ASTM E 799 are based on a distribution of liquid droplets (particles) ranging from 240 – 6532 μm. For this distribution the following results were calculated:

D10	= 1460 μm
D32	= 2280 μm
D50	= 2540 μm
D43	= 2670 μm

These results are fairly typical in that the D₄₃ is larger than the D₅₀ – the volume-basis median value.

Median

Median values are defined as the value where half of the population resides above this point, and half resides below this point. For particle size distributions the median is called the D₅₀ (or x50 when following certain ISO guidelines). The D₅₀ is the size in microns that splits the distribution with half above and half below this diameter. The D_{v,50} is the median for a volume distribution, D_{n,50} is used for number distributions, and D_{s,50} is used for surface distributions. Since the primary result from laser diffraction is a volume distribution, the default D₅₀ cited is the volume median and D₅₀ typically refers to the D_{v,50} without including the v. This value is one of the easier statistics to understand and also one of the most meaningful for particle size distributions.



Mode

The mode is the peak of the frequency distribution, or it may be easier to visualize it as the highest peak seen in the distribution. The mode represents the particle size (or size range) most commonly found in the distribution. Less care is taken to denote whether the value is based on volume, surface or number, so either run the risk of assuming volume basis or check to assure the distribution basis. The mode is not as commonly used, but can be descriptive; in particular if there is more than one peak to the distribution, then the modes are helpful to describe the mid-point of the different peaks.

For non-symmetric distributions the mean, median and mode will be three different values shown in Figure 2 below.

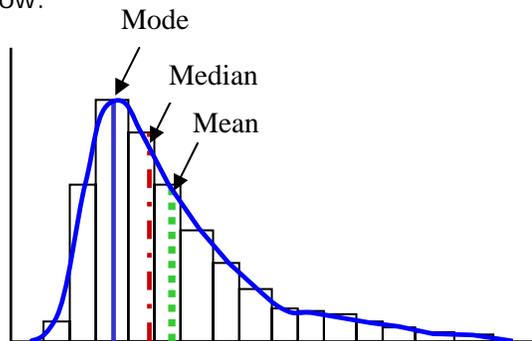


Figure 2: A non-symmetric distribution

Distribution Widths

Most instruments are used to measure the particle size distribution, implying an interest in the width or breadth of the distribution. Experienced scientists typically shun using a single number answer to the question 'what size are those particles?', and prefer to include a way to define the width. The field of statistics provides several calculations to describe the width of distributions, and these calculations are sometimes

used in the field of particle characterization. The most common calculations are standard deviation and variance. The standard deviation (St Dev.) is the preferred value in our field of study. As shown below in Figure 3, 68.27% of the total population lies within +/- 1 St Dev, and 95.45% lies within +/- 2 St Dev.

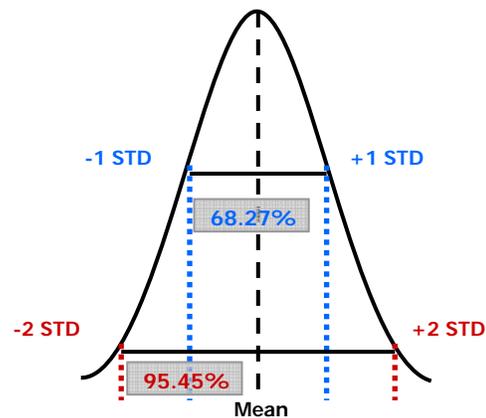


Figure 3: The Mean value flanked by 1 and 2 standard deviation points for a normal distribution

Although occasionally cited, the use of standard deviation declined when hardware and software advanced beyond assuming normal or Rosin-Rammler distributions.

Once "model independent" algorithms were introduced many particle scientists began using different calculations to describe distribution width. One of the common values used for laser diffraction results is the span, with the strict definition shown in the equation below (2):

$$\text{Span} = \frac{D_{v0.9} - D_{v0.1}}{D_{v0.5}}$$

In rare situations the span equation may be defined using other values such as $D_{v0.8}$ and $D_{v0.2}$. Laser



diffraction instruments should allow the user this flexibility.

An additional approach to describing distribution width is to normalize the standard deviation through division by the mean. This is the Coefficient of Variation (COV) (although it may also be referred to as the relative standard deviation, or RSD). Although included in HORIBA laser diffraction software this value is seldom used as often as it should given its stature. The COV calculation is both used and encouraged as a calculation to express measurement result reproducibility. ISO13320 (4) encourages all users to measure any sample at least 3 times, calculate the mean, st dev, and COV (st dev/mean), and the standard sets pass/fail criteria based on the COV values.

Another common approach to define the distribution width is to cite three values on the x-axis, the D10, D50, and D90 as shown in Figure 4. The D50, the median, has been defined above as the diameter where half of the population lies below this value. Similarly, 90 percent of the distribution lies below the D90, and 10 percent of the population lies below the D10.

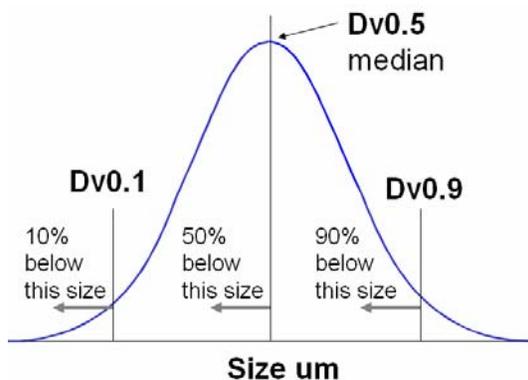


Figure 4: D10, D50, and D90 values

Technique Dependence

HORIBA Instruments, Inc. distributes particle characterization tools based on several principles including laser diffraction, dynamic light scattering, acoustic attenuation, and image analysis. Each of these techniques generates results in both similar and unique ways. Most techniques can describe results using standard statistical calculations such as the mean and standard deviation. But commonly accepted practices for describing results have evolved for each technique.

Laser Diffraction

All of the calculations described in this document are generated by the HORIBA laser diffraction software package. Results can be displayed on a volume, surface area, or number basis. Statistical calculations such as standard deviation and variance are available in either arithmetic or geometric forms, but are rarely used. The most common approach for expressing laser diffraction results is to report the D10, D50, and D90 values based on a volume distribution. The span calculation is the most common format to express distribution width. That said, there is nothing wrong with using any of the available calculations, and indeed many customers include the D4,3 when reporting results.

A word of caution is given when considering converting a volume distribution into either a surface area or number basis. Although the conversion is supplied in the software, it is only provided for comparison to other techniques, such as microscopy, which inherently measure particles on different bases. The conversion is only valid for symmetric distributions and



should not be used for any other purpose than comparison to another technique.

Dynamic Light Scattering

Dynamic Light Scattering (DLS) is unique among the techniques described in this document. The primary result from DLS is typically the mean value from the intensity distribution (called the Z average) and the polydispersity index (PDI) to describe the distribution width. It is possible to convert from an intensity to a volume distribution if the refractive index of the sample is known. The HORIBA DLS software makes this conversion easy and therefore many HORIBA customers report D10, D50, and D90 values from the volume distribution.

Acoustic Spectroscopy

The DT-series instruments based on acoustic spectroscopy model the result assuming normal distributions with either one or two peaks, based on a volume distribution. When assuming a normal distribution, the result can be completely described by the mean and standard deviation – which is one common approach for reporting results from the DT systems. The results are also automatically reported as D10, D50, and D90, both for single and bi-modal distributions.

Image Analysis

The primary results from image analysis are based on number distributions. These are often converted to a volume basis, and in this case this is an accepted and valid conversion. Image analysis provides far more data values and options than any of the other techniques described in this document. Measuring each

particle allows the user unmatched flexibility for calculating and reporting particle size results.

Image analysis instruments may report distributions based on particle length as opposed to spherical equivalency, or they may build volume distributions based on shapes other than spheres.

Dynamic image analysis tools such as the CAMSIZER allow users to choose a variety of length and width descriptors such as the maximum Feret diameter and the minimum largest chord diameter as described in ISO 13322-2 (5).

With the ability to measure particles in any number of ways comes the decision to report those measurements in any number of ways. Users are again cautioned against reporting a single value – the number mean being the worst choice of the possible options. Experienced particle scientists often report D10, D50, and D90, or include standard deviation or span calculations when using image analysis tools.

Conclusions

All particle size analysis instruments provide the ability to measure and report the particle size distribution of the sample. There are very few applications where a single value is appropriate and representative. The modern particle scientist often chooses to describe the entire size distribution as opposed to just a single point on it. (One exception might be extremely narrow distributions such as latex size standards where the width is negligible.) Almost all real world samples exist as a distribution of particle sizes and it is recommended to report the width of the distribution for



any sample analyzed. The most appropriate option for expressing width is dependent on the technique used. When in doubt, it is often wise to refer to industry accepted standards such as ISO or ASTM in order to conform to common practice.

References:

1. ISO 9276-2:2001 :
Representation of results of particle size analysis --
Part 2: Calculation of average particle sizes/diameters and moments from particle size distributions
2. ASTM E 799-03 Standard Practice for Determining Data Criteria and Processing for Liquid Drop Size Analysis
3. TN154, Particle Size Result Interpretation: Number vs. Volume Distributions, available at www.horibalab.com
4. ISO 13320-1 Particle size analysis – Laser diffraction methods
5. ISO 13322-2 Particle size analysis - Image analysis methods - Part 2: Dynamic image analysis methods

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