

Connected Autonomous Vehicles (CAVs) lab-based testing applications close the gap between simulation, Hardware-in-the-Loop (HIL) tests and proving ground tests. Enabling scenario-based testing procedures for vehicles and sensors, ensuring reliable results and a maximum of reproducibility.

HORIBA's CAV test applications (patents pending) contribute to validation processes during Vehicle-in-the-Loop (VIL) tests and help develop Advanced Driver Assistance Systems (ADAS) and Autonomous Driving.

With a combination of standard test procedures and our CAV testing applications for LIDAR (Light Detection and Ranging), radar and camera as a VIL solution HORIBA provides scenario-based testing with a clean stimulation and correct influences for autonomous vehicle sensors. Thereby improving the efficiency of test cycles by delivering cost-effective, reproducible test results.

FEATURES

- » Integrated sensor stimulation solution
- » Reliable data correlation between real world and simulation
- » Covering object and event detection according to upcoming regulations i.e. UN regulation on level 3 vehicle automation



KEY BENEFITS



COST-EFFECTIVE

- » High reproducibility of tests and resulting data
- » Combining simulations with vehicle stimulations



FLEXIBLE

- » Suitable for most vehicles and other LIDAR integrated means of transport and products
- » Supports development capabilities
- » Adjustable to testing requirements and onsite conditions



INTUITIVE

- » Easy-to-use with STARS Enterprise laboratory management system
- » Ready to use “plug & play” solution

APPLICATIONS

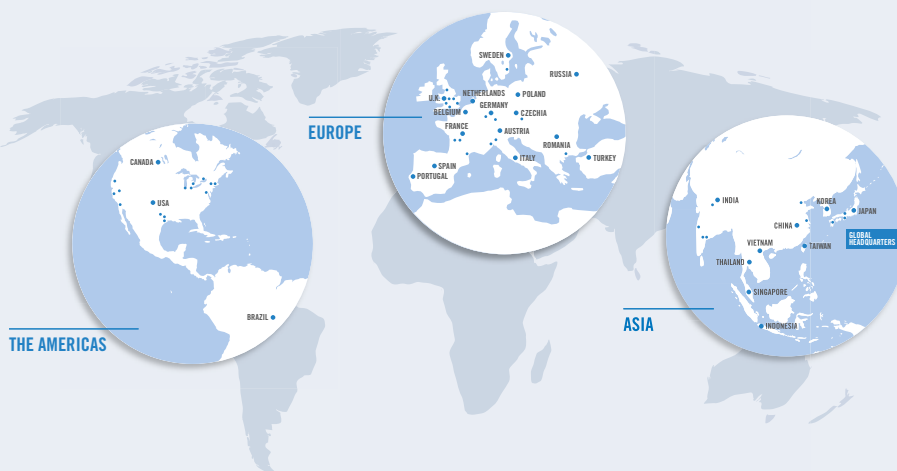
- » VIL test procedures for ADAS and CAV including steering
- » Scenario-based-testing for ADAS and CAV on a chassis dyno i. e. HORIBA Test Center or at customer site
- » Homologation and technical inspection
- » Research and development i. e. LIDAR

A COOPERATION OF:

HORIBA



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